

**CHANNEL ENCODING/DECODING APPARATUS AND METHOD FOR COMMUNICATION SYSTEM**

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Cited Documents: WO9106165; EP0643493

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**Abstract**

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A channel encoder/decoder apparatus varies an iterative decoding number according to service type, data class and channel condition. A message information receiver receives information about a message to be received. A controller determines an iterative decoding number of a decoder according to the message information received. A decoder iteratively decodes the received message according to the determined iterative decoding number. The message information includes a class of received data, and the class includes a required bit error rate (BER). The iterative decoding number is increased for a lower BER. Further, the class includes a permissible time delay, and the iterative decoding number is increased for a longer permissible time delay. In addition, the message information includes a service type of received data, and the iterative decoding number is decreased when the service type is a moving picture service.

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CHANNEL ENCODING/DECODING  
APPARATUS AND METHOD FOR COMMUNICATION SYSTEM

**BACKGROUND OF THE INVENTION**

5        1. Field of the Invention

The present invention relates generally to a channel encoding/decoding apparatus and method for a communication system, and more particularly, to a channel encoding/decoding apparatus and method for performing soft-decision iterative decoding.

2. Description of the Related Art

10        A turbo encoder is a typical channel encoder which supports iterative decoding. The turbo encoder is classified into a parallel turbo encoder and a serial turbo encoder. Although the present invention will be described with reference to the parallel turbo encoder, it is also possible to apply the present invention to the serial turbo encoder interworking with an iterative decoding apparatus.

15        The turbo encoder encodes an N-bits input data frame into parity symbols using two simple parallel concatenated codes, wherein recursive systematic convolutional (RSC) codes are generally used for component codes.

      FIGs. 1 and 2 illustrate conventional turbo encoder and decoder, respectively, which are disclosed in detail in U.S. Pat. No. 5,446,747, issued on Aug. 29, 1995, which is  
20 incorporated herein by reference.

Referring to FIG. 1, an interleaver 16 is connected between first and second constituent encoders 12 and 14. For the first and second encoders 12 and 14, a RSC encoder may be used, which is well-known in the art. The interleaver 16 has the same size as a frame length,  $N$ , of the input data, and changes arrangement of the input data bit stream  $d_k$  provided to the second constituent encoder 14 to decrease the correlation among the data bits. Therefore, the output parallel concatenated codes for the input data bitstream  $d_k$  become  $x_k$  (i.e.,  $d_k$  without modification) and  $y_{1k}$ , and  $y_{2k}$ .

FIG. 2 is a block diagram showing a configuration of a conventional turbo decoder. The turbo decoder includes an adder 18, subtracters 20 and 22, a soft-decision circuit 24, delays 26, 28 and 30, and MAP (Maximum A Posteriori Probability) decoders 32 and 34. The turbo decoder further includes an interleaver 36 which is identical to the interleaver 16 shown in FIG. 1, and deinterleavers 38 and 40. The turbo decoder iteratively decodes input data in the frame unit using a MAP decoding algorithm; a bit error rate (BER) is decreased, as the iterative decoding number increases. Generally, not only a MAP decoder but also a SOVA (Soft Output Viterbi Algorithm) decoder, which can perform soft-decision iterative decoding, can be used for the turbo decoder.

As illustrated in FIG. 1, the turbo encoder includes the interleaver 16, which implies that encoding and decoding should be performed in the frame unit. Therefore, it can be understood that the required memory capacity for the MAP decoders 32 and 34 in the turbo decoder of FIG. 2 increases in proportion to a value obtained by multiplying the frame length by a status number of the encoders 12 and 14 of FIG. 1.

In a communication system for providing various services, such as voice, character, image and moving picture services, a data rate ranges from several Kbps to several Mbps, and a length of data frames inputted to a channel encoder varies from several ms (milliseconds) to several hundred ms. In particular, a channel decoder employing the

iterative decoding, such as the turbo decoder, has the decreased bit error rate (BER) as the number of iterative decodings increases. However, an increase in the iterative decoding number inevitably leads to increases in the amount of calculations, power consumption of the decoder, and time delay. Hence, in the channel decoder using iterative decoding, the  
5 iterative decoding number is generally fixed to a value satisfying a permissible time delay irrespective of the service type.

However, since the condition of a transmission channel varies with time, a desired bit error rate may not be obtained with the fixed iterative decoding number in the worst channel condition. In a packet data service which may be less influenced by a transmission  
10 time delay, a desired bit error rate may be satisfied by increasing the iterative decoding number. However, when the iterative decoding number is fixed to a maximum value in consideration of only the worst channel condition, the amount of calculations unnecessarily increases, causing an increase in the power consumption of the decoder in a good channel condition. Further, even though the transmission delay time increases, it is needed to  
15 increase the iterative decoding number, if necessary, according to a class of the user or received data. The bit error rate and the time delay are determined according to the class. Therefore, it is necessary to vary the iterative decoding number according to the service type, the class, and the channel conditions.

### SUMMARY OF THE INVENTION

20 It is, therefore, an object of the present invention to provide a channel encoding/decoding apparatus and method for varying an iterative decoding number according to a service type and a data class.

It is another object of the present invention to provide a channel encoding/decoding apparatus for varying an iterative decoding number according to a channel condition

varying with time.

The present invention provides a receiving device for a communication system. In the receiving device, a message information receiver receives information about a message to be received. A controller determines an iterative decoding number of a decoder  
5 according to the message information received. A decoder iteratively decodes the received message according to the determined iterative decoding number.

The message information includes a class of received data, and the class includes a required bit error rate (BER). The iterative decoding number is increased for a lower BER. Further, the class includes a permissible time delay, and the iterative decoding number is  
10 increased for a longer permissible time delay.

In addition, the message information includes a service type of received data, and the iterative decoding number is decreased when the service type is a moving picture service because the service should be perform short delay time.

### BRIEF DESCRIPTION OF THE DRAWINGS

15 The above and other objects, features and advantages of the present invention will become more apparent from the following detailed description when taken in conjunction with the accompanying drawings in which:

FIG. 1 is a block diagram illustrating a conventional turbo encoder;

FIG. 2 is a block diagram illustrating a conventional turbo decoder;

20 FIG. 3 is a block diagram illustrating a channel transmitter according to a preferred embodiment of the present invention;

FIG. 4 is a block diagram illustrating a channel receiver according to a preferred embodiment of the present invention;

FIG. 5 is a block diagram illustrating another channel receiver according to another preferred embodiment of the present invention;

FIG. 6 is a flow chart illustrating a control process of an iterative decoding controller according to an embodiment of the present invention; and

5        FIG. 7 is a graph illustrating a simulation result as a function of the iterative decoding number according to a preferred embodiment of the present invention.

### **DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT**

A preferred embodiment of the present invention will be described hereinbelow with reference to the accompanying drawings. In the following description, well known  
10        constructions or functions are not described in detail so as not to obscure the present invention.

In a preferred embodiment of the present invention, a turbo encoder is used for a channel encoder, and a MAP decoder is used for soft-decision iterative decoding. A SOVA decoder can also be used for the soft-decision iterative decoding.

15        FIG. 3 illustrates a channel transmitter including a turbo channel encoder according to a preferred embodiment of the present invention. The turbo channel encoder turbo encodes user data received in a unit of N-bits input frame and transmits the encoded user data over a transmission channel.

A source data encoder 312 compresses and encodes user data provided from a user  
20        data input device 311. A channel encoder 313 encodes an output of the source data encoder 312. In the embodiment, a turbo encoder is used for the channel encoder 313. A channel interleaver 314 interleaves an output of the channel encoder 313. A modulator 315 modulates (or spreads) an output of the interleaver 314 and transmits the modulated output

over a transmission channel 316. A central processing unit (CPU) 300 determines a service type (voice, character, image, or moving picture service) and a data class, and provides message information about the service type and data class to a message information transmitter 301. The data class includes the required bit error rate (BER) and the  
5 permissible time delay. The data class and service type can be previously determined not only during call setup but also during on service.

In operation, upon receipt of the user data from the user data input device 311, the source data encoder 312 encodes the user data and provides the encoded data to the channel encoder 313. The user data may be character, image or moving picture data having  
10 a data rate of several tens of Kbps or more as well as voice data having a data rate of several Kbps. The CPU 300 transmits message information about the service type and the class of the user data through the message information transmitter 301.

Although the present invention is described with reference to an embodiment which transmits the message information to the decoder via a separate channel, it is also possible  
15 to transmit the message information by carrying it on a head or tail area of a transmission frame during transmission of the user data.

FIG. 4 illustrates a channel receiver including a channel decoder according to a preferred embodiment of the present invention.

Referring to FIG. 4, a demodulator 412 demodulates an input signal received via  
20 a transmission channel 411. A channel deinterleaver 413 deinterleaves an output of the demodulator 412. A message information receiver 401 receives the message information transmitted from the message information transmitter 301 of FIG. 3, and provides it to a CPU 400. The CPU 400 analyzes the received message information and provides information about iterative decoding to an iterative decoding controller 402. The iterative

decoding controller 402 then analyzes the iterative decoding information provided from the CPU 400 to determine the iterative decoding number according to the analysis, and controls the soft-decision decoder 414 according to the determined iterative decoding number. Here, the iterative decoding number is decreased for a moving picture service permitting only a short time delay, and increased for a character service permitting even a longer time delay. In addition, even while decoding, if the BER or FER (Frame Error Rate) is higher than a threshold, the iterative decoding number is increased. The soft-decision decoder 414 iteratively decodes an output of the channel deinterleaver 413 under the control of the iterative decoding controller 402. A MAP or SOVA decoder may be used for the soft-decision decoder 414. A source data decoder 415 decodes an output of the soft-decision decoder 414 and provides the decoded output to a user data output device 416.

The message information includes the service type (voice, character, image and moving picture service) and the data class, as previously stated. The data class includes the required BER and the permissible time delay. This message information is used to determine the iterative decoding number. For the lower BER or the longer permissible time delay, the iterative decoding controller 402 increases the iterative decoding number.

The channel decoder 414 iteratively decodes the user data according to the iterative decoding number control signal provided from the iterative decoding controller 402. Upon receiving the frame data through the transmission channel 411, the demodulator 412 demodulates the received data and supplies the demodulated data to the channel deinterleaver 413. The channel deinterleaver 413 deinterleaves the demodulated data and provides the deinterleaved data to the decoder 414. At this moment, the message information receiver 401 receives the message information about the service type and the data class transmitted from the message information transmitter 301 of FIG. 3 via the transmission channel and provides the received message information to the CPU 400. The CPU 400 then analyzes the message information and provides information about iterative



decoding to the iterative decoding controller 402. The iterative decoding controller 402 analyzes the information about the iterative decoding to determine the iterative decoding number. Based on the determination results, the iterative decoding controller 402 varies the iterative decoding number of the soft-decision decoder 414, when necessary. The soft-  
5 decision decoder 414 iteratively decodes the output of the channel deinterleaver 413 according to the iterative decoding number control signal provided from the iterative decoding controller 402. The controller 400 controls timing of the entire decoding process according to a variation in the iterative decoding number. The output of the soft-decision decoder 414 is inputted to the user data output device 416 via the source data decoder 415.

10        FIG. 5 illustrates another channel receiver including a channel decoder according to another preferred embodiment of the present invention.

Referring to FIG. 5, the channel receiver does not include the message information transmitter 401 of FIG. 4. However, the channel receiver can be separately provided with the message information about the service type and data class from the transmitter. In the  
15 channel receiver, a channel condition analyzer 501 varies the iterative decoding number of a soft-decision decoder 514 according to the channel condition varying with time. For example, in a CDMA communication system, when a base station exchanges data with multiple mobile stations, the base station provides the respective mobile stations with an interference level signal among reverse channel signals received from the mobile stations  
20 a broadcasting channel. This interference level signal is used for channel condition in a mobile station. Alternatively, the mobile stations can determine the channel condition by analyzing a pilot signal transmitted from the base station to measure a signal-to-interference ratio (SIR) of the signal.

A demodulator 512 demodulates an input signal received through a transmission  
25 channel 511. A channel deinterleaver 513 deinterleaves an output of the demodulator 512.

The channel condition analyzer 501 analyzes a channel condition by measuring a signal-to-interference ratio (SIR) and provides the analysis results to a CPU 500. The CPU 500 provides the measured SIR information to an iterative decoding controller 502. The iterative decoding controller 502 then analyzes the received information to determine  
5 whether it is necessary to vary the present iterative decoding number and varies the iterative decoding number of the soft-decision decoder 514 according to the determination. The soft-decision decoder 514 iteratively decodes an output of the channel deinterleaver 513 under the control of the iterative decoding controller 502. The MAP or SOVA decoder may be used for the soft-decision decoder 514. A source data decoder 515 decodes an output of  
10 the soft-decision decoder 514 and provides the decoded output to a user data output device 516.

In operation, the channel condition analyzer 501 measures the SIR using an interference level control signal and a pilot signal transmitted from the base station and provides the measured SIR to the CPU 500. The CPU 500 provides information about  
15 iterative decoding to the iterative decoding controller 502. The iterative decoding controller 502 analyzes the information about the iterative decoding and determines whether to vary the present iterative decoding number of the soft-decision decoder 514. For example, the iterative decoding controller 502 determines to decrease the iterative decoding number when the condition of the transmission channel is better than a threshold. The soft-decision  
20 decoder 514 decodes the output of the channel deinterleaver 513 according to the iterative decoding number control signal from the iterative decoding controller 502. The controller 500 controls timing of the entire decoding process based on a variation in the iterative decoding number. The output of the soft-decision decoder 514 is inputted to the user data output device 516 via the source data decoder 515.

25       A description will be made as to an operation of the iterative decoding controllers

402 and 502 with reference to FIG. 6.

The iterative decoding controllers 402 and 502 receive, at step 611, information about iterative decoding from the CPU 400 and 500, respectively. The information about the iterative decoding is determined by analyzing the message information about the service  
5 type, the data class, and the present channel condition. At step 612, the information about the iterative decoding is analyzed to determine the iterative decoding number. It is judged at step 613 whether it is necessary to vary the iterative decoding number by comparing the determined iterative decoding number with a threshold. If it is judged that it is not necessary to vary the iterative decoding number, the iterative decoding controllers 402 and 502 output  
10 the iterative decoding number control signal in a first state to the soft-decision decoders 414 and 514, respectively, at step 615. Otherwise, when it is necessary to vary the iterative decoding number, the present iterative decoding number is varied to the determined iterative decoding number at step 614. Thereafter, a corresponding iterative decoding number control signal in a second state is applied to the soft-decision decoders 414 and 514  
15 at step 615.

FIG. 7 is a graph illustrating a simulation result as a function of the iterative decoding number of the channel decoder. As shown in FIG. 7, there is a considerable difference in the bit error rate between 4-times iterative decoding and 8-times iterative decoding. To provide a service having a higher data class in the state where the iterative  
20 decoding number is initially set to 4, the iterative decoding number is increased to 8.

In the light of the foregoing descriptions, an efficiency of the turbo decoder can be increased by varying the iterative decoding number according to the service type, data class and channel condition.

While the invention has been shown and described with reference to a certain

preferred embodiment thereof, it will be understood by those skilled in the art that various changes in form and details may be made therein without departing from the spirit and scope of the invention as defined by the appended claims.

**WHAT IS CLAIMED IS:**

1. A receiving device for a communication system, comprising:  
a message information receiver for receiving information about a message to be received;  
5 a controller for determining an iterative decoding number of a decoder according to the message information received; and  
a decoder for iteratively decoding the received message according to the determined iterative decoding number.
2. The receiving device as claimed in claim 1, wherein the message information  
10 includes a class of received data.
3. The receiving device as claimed in claim 2, wherein the class includes a required bit error rate (BER).
4. The receiving device as claimed in claim 3, wherein the iterative decoding number is increased for a lower BER.
- 15 5. The receiving device as claimed in claim 2, wherein the class includes a permissible time delay.
6. The receiving device as claimed in claim 5, wherein the iterative decoding number is increased for a longer permissible time delay.
7. The receiving device as claimed in claim 1, wherein the message information  
20 includes a service type of received data.

8. The receiving device as claimed in claim 7, wherein the iterative decoding number is decreased when the service type is a moving picture service.
9. The receiving device as claimed in claim 1, wherein the decoder is a soft-decision decoder.
- 5 10. The receiving device as claimed in claim 1, wherein the decoder is a MAP (Maximum A Posteriori Probability) decoder.
11. The receiving device as claimed in claim 1, wherein the decoder is a SOVA (Soft Output Viterbi Algorithm) decoder.
12. A receiving device for a communication system, comprising:  
10 a channel condition analyzer for analyzing a condition of a receiving channel;  
a controller for determining an iterative decoding number of a decoder according to the channel condition analysis; and  
the decoder for iteratively decoding a received message according to the determined iterative decoding number.
- 15 13. The receiving device as claimed in claim 12, wherein the iterative decoding number is increased for a bad channel condition.
14. The receiving device as claimed in claim 12, wherein the decoder is a soft-decision decoder.
15. The receiving device as claimed in claim 12, wherein the decoder is a MAP  
20 decoder.

16. The receiving device as claimed in claim 12, wherein the decoder is a SOVA decoder.

17. A receiving method for a communication system, comprising the steps of:  
receiving information about a message to be received;  
5 determining an iterative decoding number of a decoder according to the message  
information received; and  
iteratively decoding the received message according to the determined iterative  
decoding number.

18. The receiving method as claimed in claim 17, wherein the message  
10 information includes a class of received data.

19. The receiving method as claimed in claim 18, wherein the iterative decoding  
number is decreased for a lower class.

20. The receiving method as claimed in claim 18, wherein the class includes a  
required BER.

15 21. The receiving method as claimed in claim 18, wherein the iterative decoding  
number is decreased for a higher BER.

22. The receiving method as claimed in claim 18, wherein the class includes a  
permissible time delay.

23. The receiving method as claimed in claim 22, wherein the iterative decoding  
20 number is decreased for a shorter permissible time delay.

24. The receiving method as claimed in claim 17, wherein the message information includes a service type of received data.

25. The receiving method as claimed in claim 28, wherein the iterative decoding number is decreased when the service type is a moving picture service.

5        26. A receiving method for a communication system, comprising the steps of:  
analyzing a condition of a receiving channel;  
determining an iterative decoding number of a decoder according to the channel  
condition analysis; and  
iteratively decoding a received message according to the determined iterative  
10 decoding number.

27. The receiving method as claimed in claim 26, wherein the channel condition is determined according to a signal-to-interference ratio (SIR) of a received signal.

28. The receiving method as claimed in claim 27, wherein the iterative decoding number is decreased for the channel condition being worse than a threshold.



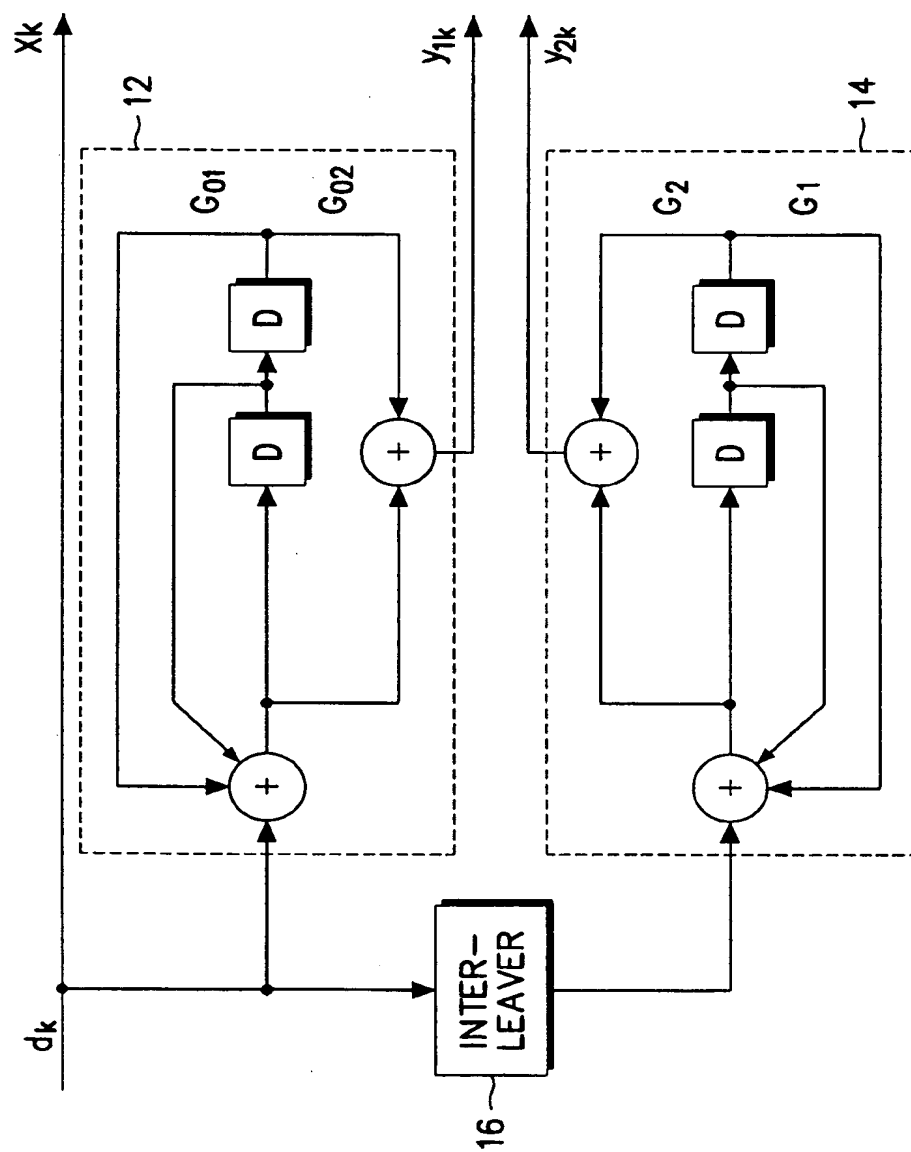


FIG. 1

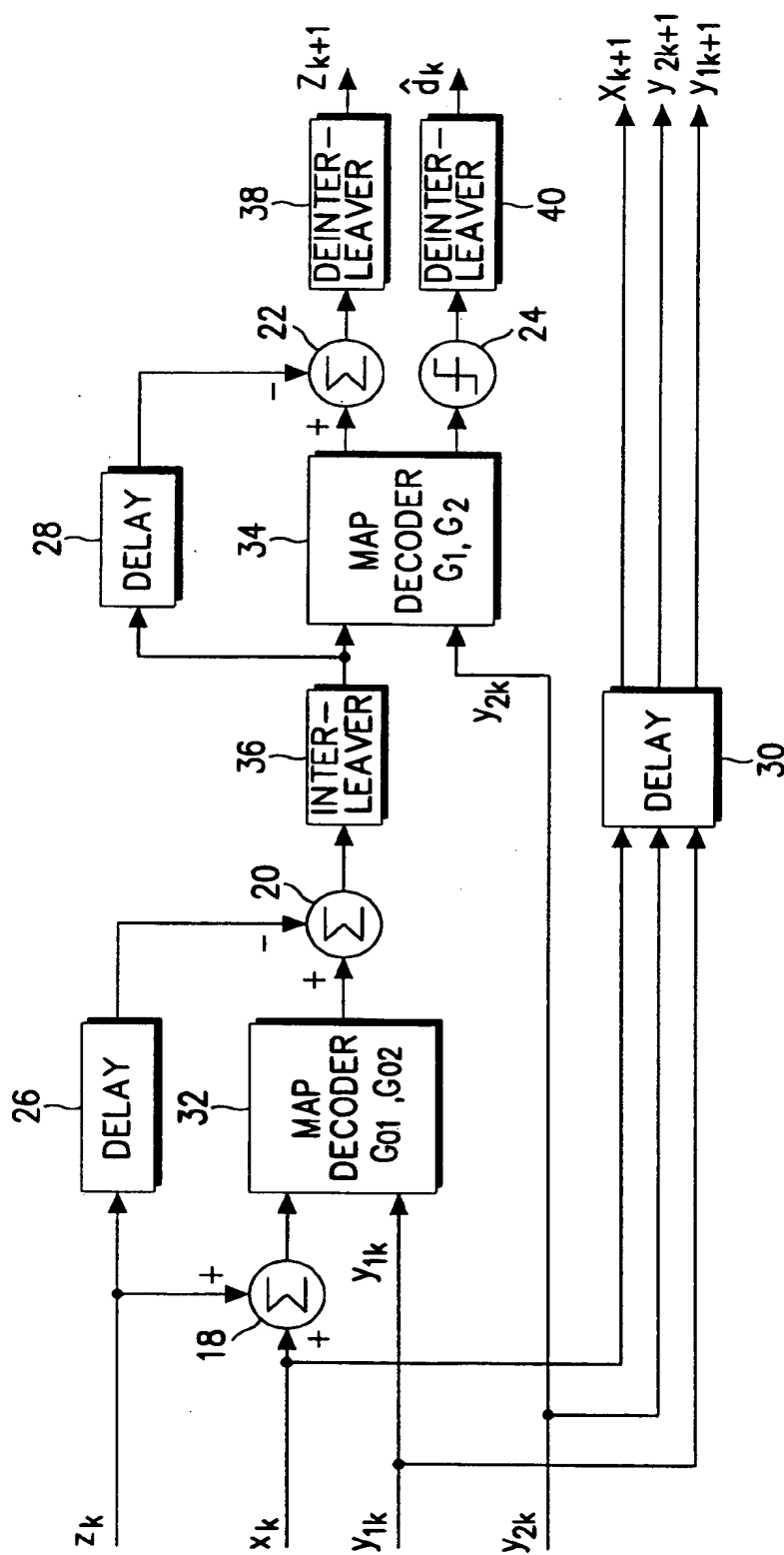


FIG. 2

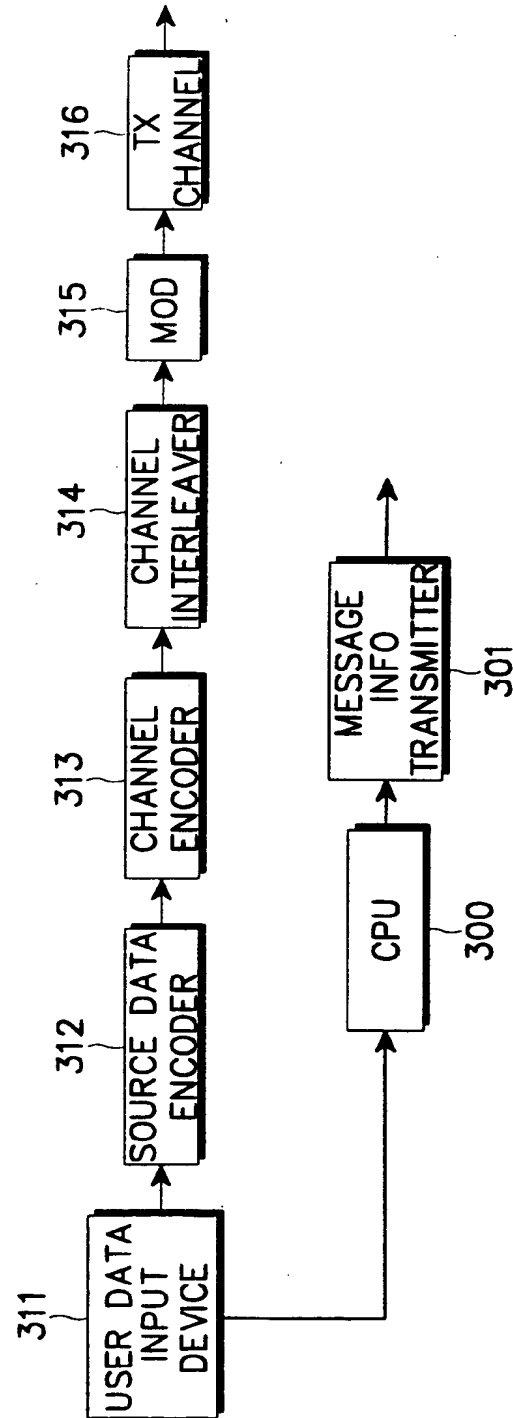


FIG. 3

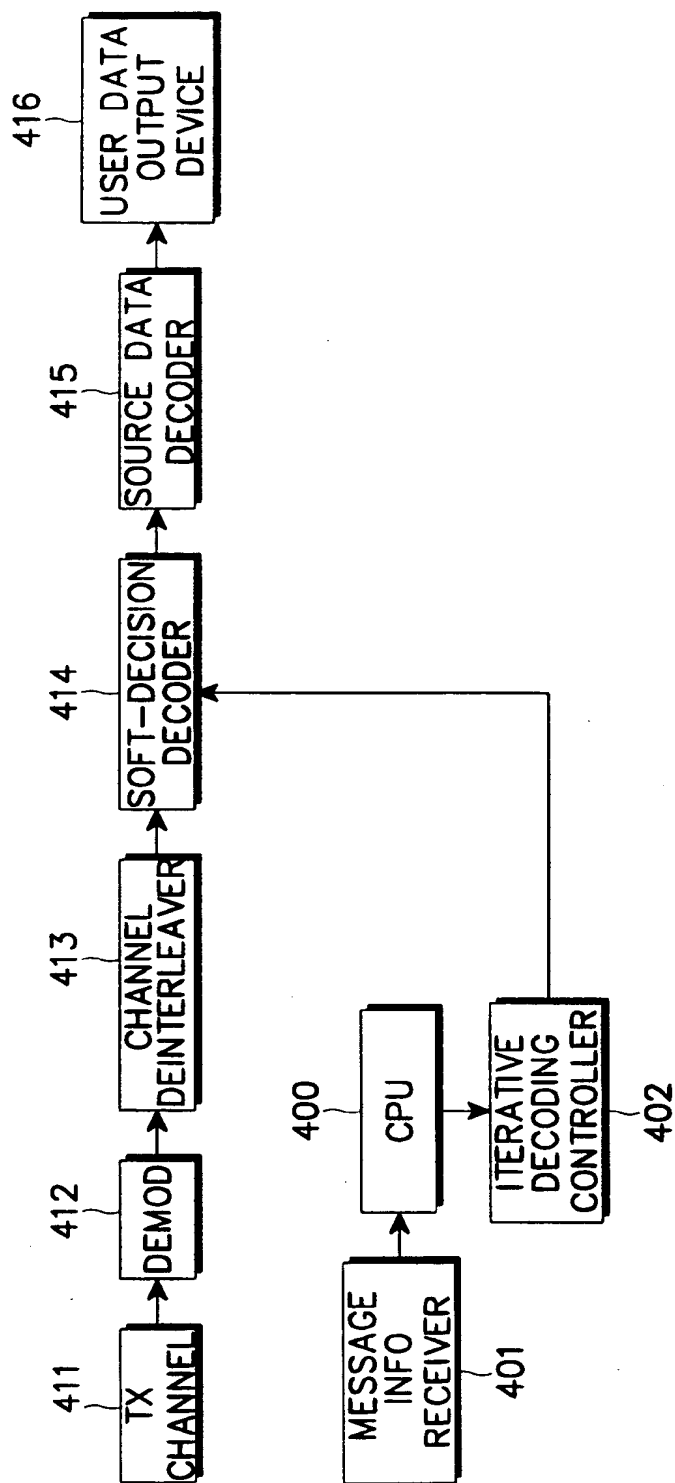


FIG. 4

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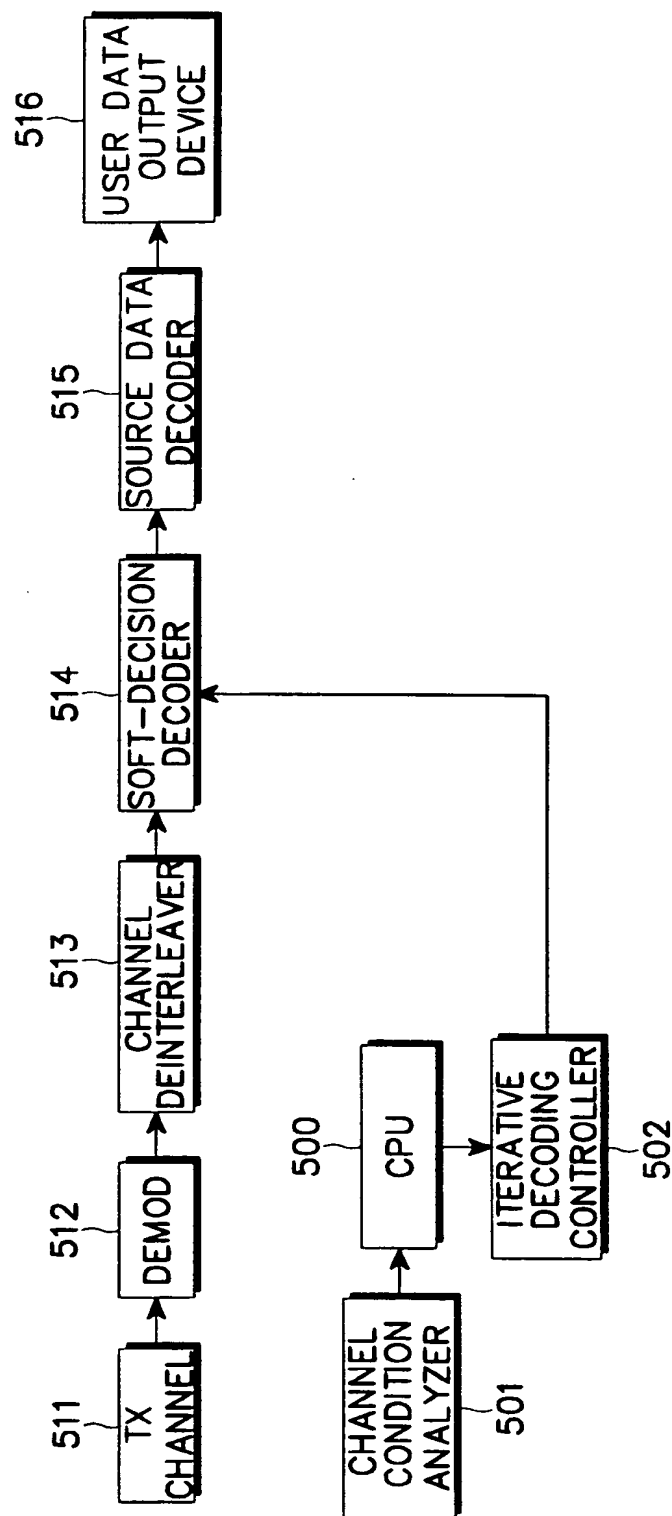


FIG. 5

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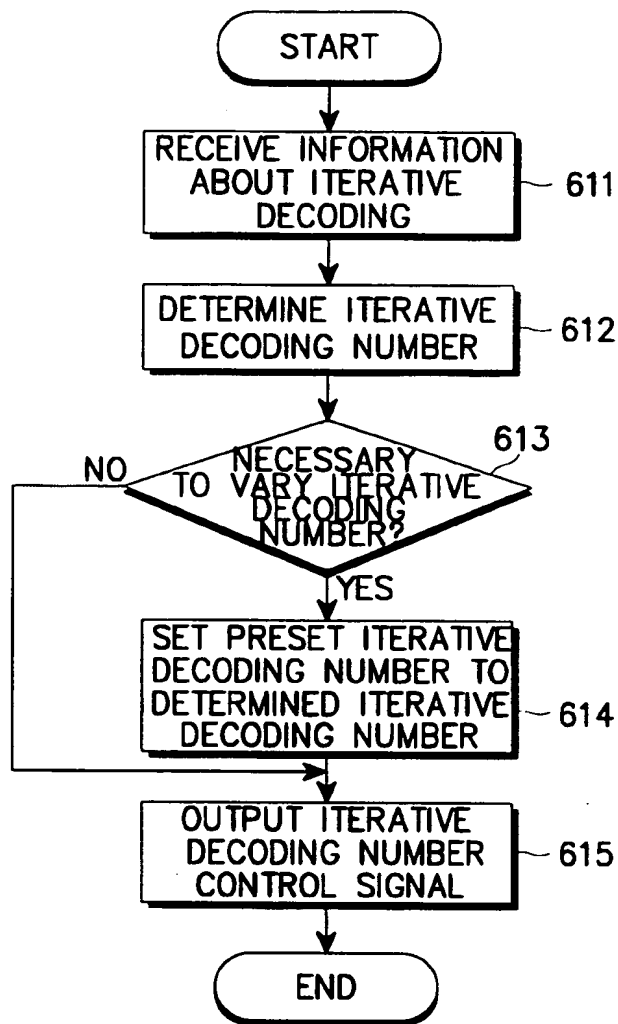


FIG. 6

WCDMA, antenna diversity, 2-finger RAKE, no power control

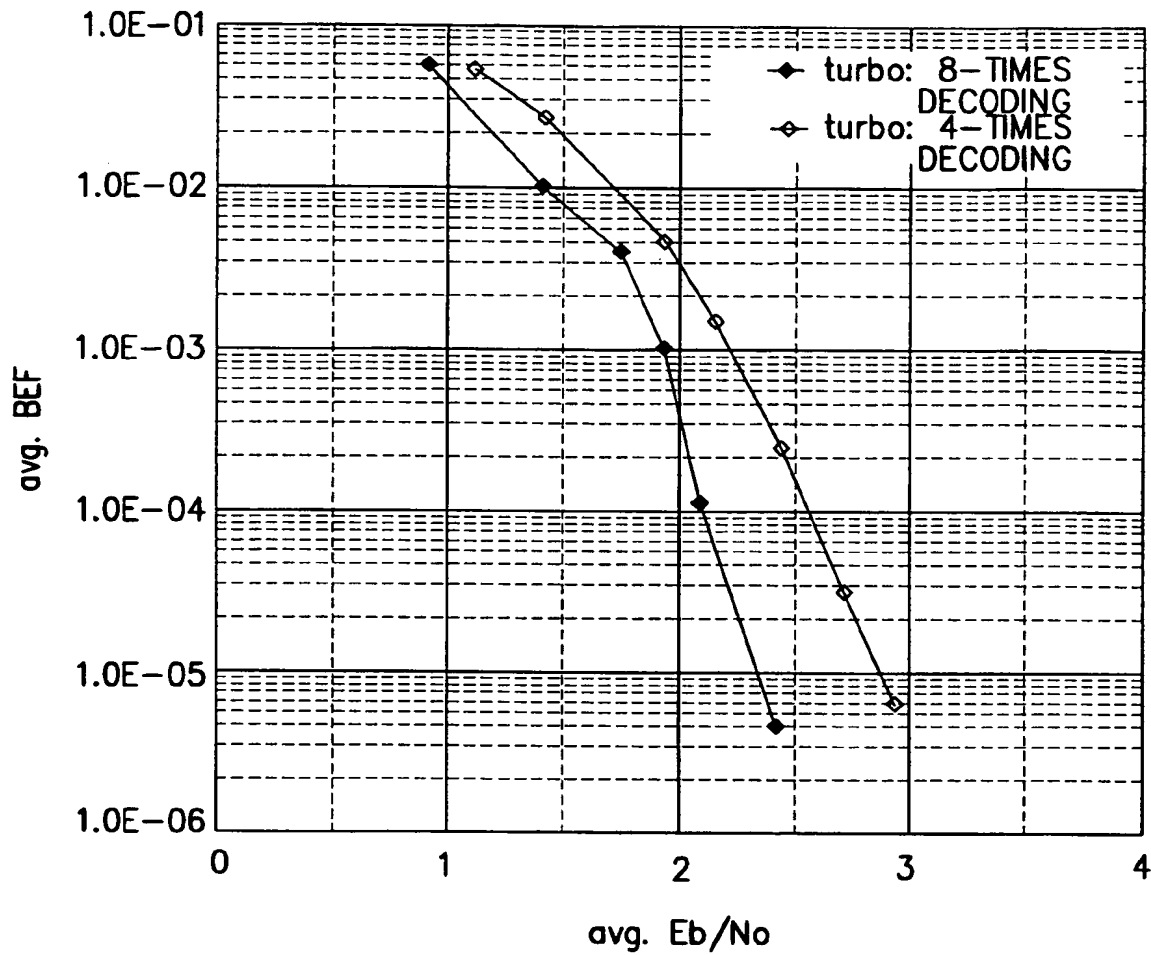


FIG. 7

# INTERNATIONAL SEARCH REPORT

International application No.  
PCT/KR 99/00186

## A. CLASSIFICATION OF SUBJECT MATTER

IPC<sup>6</sup>: H 03 M 13/00

According to International Patent Classification (IPC) or to both national classification and IPC

## B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC<sup>6</sup>: H 03 M 13/00; H 04 L 27/00

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

WPI

## C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	WO 91/6 165 A1 (MOTOROLA INC.), 02 May 1991 (02.05.91), totality.	1,12,17,26
A	EP 0 643 493 A1 (HUGHES AIRCRAFT COMPANY), 15 March 1995 (15.03.95), description; fig.1-9.  ----	1,12,17,26

☐ Further documents are listed in the continuation of Box C.

☒ See patent family annex.

\* Special categories of cited documents:

„A“ document defining the general state of the art which is not considered to be of particular relevance

„E“ earlier application or patent but published on or after the international filing date

„L“ document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)

„O“ document referring to an oral disclosure, use, exhibition or other means

„P“ document published prior to the international filing date but later than the priority date claimed

„T“ later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

„X“ document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

„Y“ document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

„&“ document member of the same patent family

Date of the actual completion of the international search

30 July 1999 (30.07.99)

Date of mailing of the international search report

24 August 1999 (24.08.99)

Name and mailing address of the ISA/AT  
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# INTERNATIONAL SEARCH REPORT

In ternational application No.  
PCT/KR 99/00186

## Box I Observations where certain claims were found unsearchable (Continuation of item 1 of first sheet)

This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☐ Claims Nos.:  
because they relate to subject matter not required to be searched by this Authority, namely:
2. ☐ Claims Nos.:  
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3. ☒ Claims Nos.: 25: the reference to claim 28 must be wrong  
~~because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).~~

## Box II Observations where unity of invention is lacking (Continuation of item 2 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1. ☐ As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.
2. ☐ As all searchable claims could be searched without effort justifying an additional fee, this Authority did not invite payment of any additional fee.
3. ☐ As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4. ☐ No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims: it is covered by claims Nos.:

Remark on Protest

- ☐ The additional search fees were accompanied by the applicant's protest.  
☐ No protest accompanied the payment of additional search fees.

## INTERNATIONAL SEARCH REPORT

International application No.  
PCT/KR 99/00186

The subject matter of the WO 91/06 165 A1 is soft decision decoding with channel equalization. A mechanism for soft decision decoding is provided for tune-dispersed signals in a communications network. It comprises the reception of tune-dispersed signals, the recovering of information contained in the signal, multiplying the recovered information with the absolute value of that at-least-partly-equalized signal, and error-correction of the multiplied information by a Viterbi algorithm channel decoding scheme of error correction.

The EP 0 643 493 A1 shows high performance error control coding in channel encoders and decoders. The error control coding scheme exploits the nonlinear block codes for purposes of tailoring those codes to a fading channel in order to provide superior error protection to the compressed half rate data. A CRC is also used to futher reduce the BER.

# INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.

PCT/KR 99/00186

In Recherchenbericht angeführtes Patentdokument Patent document cited in search report Document de brevet cité dans le rapport de recherche			Datum der Veröffentlichung Publication date Date de publication	Mitglied(er) der Patentfamilie Patent family member(s) Membre(s) de la famille de brevets	Datum der Veröffentlichung Publication date Date de publication
WO	A	016165		keine - none - rien	
EP A1		643493	15-03-1995	AT E 139071	15-06-1996
				CA AA 2131674	11-03-1995
				CN A 1128917	14-08-1996
				DE CO 69400228	11-07-1996
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